

Report #29

Partial Derivatives for Various
Scalar Functions of Matrices

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INTRODUCTION

This paper computes the partial derivative of the scalar function $\phi = \text{tr}(BAB^T) - \text{tr}\{M^T[(BAB^T)^{-1} - (BDB^T)^{-1} - I_k]\}$ with respect to the matrices B and D where:

tr ; the trace of a matrix

B ; a k by n real matrix of rank $k \leq n$

Λ ; an n by n positive definite, real symmetric matrix

M ; a real k by k symmetric matrix (assumed to be constant)

D ; an n by n positive definite diagonal matrix

I_k ; the k by k identity matrix

DISCUSSION - Define the scalar

$$\phi_1 = \frac{1}{2} \text{tr}(BAB^T)$$

We use the notation $\frac{\partial \phi_1}{\partial B}$ to denote the matrix $\left(\frac{\partial \phi_1}{\partial b_{ij}}\right)$ where $B = (b_{ij})$

Lemma 1 $\left(\frac{\partial \phi_1}{\partial B}\right)^T = \Lambda B^T$, so that $\phi_1 = \frac{1}{2} \text{tr}\left[B\left(\frac{\partial \phi_1}{\partial B}\right)^T\right]$

Proof: $\frac{\partial \phi_1}{\partial b_{ij}} = \frac{1}{2} \text{tr}\left[\frac{\partial B}{\partial b_{ij}} \Lambda B^T + B \Lambda \frac{\partial B^T}{\partial b_{ij}}\right] = \frac{1}{2} \text{tr}\left[\left(\frac{\partial B}{\partial b_{ij}} \Lambda B^T\right) + \left(\frac{\partial B}{\partial b_{ij}} \Lambda B^T\right)^T\right]$

But for any square matrices A_1 and A_2 , $\text{tr}(A_1) = \text{tr}(A_1^T)$ and

$\text{tr}(A_1 + A_2) = \text{tr}(A_1) + \text{tr}(A_2)$ so that

$$\frac{\partial \phi_1}{\partial b_{ij}} = \text{tr}\left[\left(\frac{\partial B}{\partial b_{ij}} \Lambda B^T\right)\right] = \alpha_{ji}$$

where $\Lambda B^T = (\alpha_{ij})$

Thus it follows

$$\frac{\partial \phi_1}{\partial b_{ij}} = (\alpha_{ji}), \text{ and thus}$$

$$\left(\frac{\partial \phi_1}{\partial B} \right)^T = \left(\frac{\partial \phi_1}{\partial b_{ij}} \right)^T = (\alpha_{ji})^T = (\alpha_{ij}) = \Lambda B^T$$

proving the Lemma.

Lemma 2: $\frac{\partial}{\partial b_{ij}} (\Lambda B^T)^{-1} = -(\Lambda B^T)^{-1} \left[\frac{\partial}{\partial b_{ij}} (\Lambda B^T) \right] (\Lambda B^T)^{-1}$ where $B = (b_{ij})$

Proof: Since $(\Lambda B^T)(\Lambda B^T)^{-1} = I_k$, it follows

$$\left[\frac{\partial}{\partial b_{ij}} (\Lambda B^T) \right] (\Lambda B^T)^{-1} + (\Lambda B^T) \left[\frac{\partial}{\partial b_{ij}} (\Lambda B^T)^{-1} \right] = (0)$$

so that

$$\frac{\partial}{\partial b_{ij}} (\Lambda B^T)^{-1} = -(\Lambda B^T)^{-1} \left[\frac{\partial}{\partial b_{ij}} (\Lambda B^T) \right] (\Lambda B^T)^{-1}$$

as desired.

Lemma 3 - Let $\phi_2 = \frac{1}{2} \text{tr}[M^T (\Lambda B^T)^{-1}]$. Then $\left(\frac{\partial \phi_2}{\partial B} \right)^T = -\Lambda B^T (\Lambda B^T)^{-1} M^T (\Lambda B^T)^{-1}$

and $\phi_2 = -\frac{1}{2} \text{tr} \left[B \left(\frac{\partial \phi_2}{\partial B} \right)^T \right]$

Proof:
$$\begin{aligned} \frac{\partial \phi_2}{\partial b_{ij}} &= \frac{\partial}{\partial b_{ij}} \frac{1}{2} \text{tr}[M^T (\Lambda B^T)^{-1}] \\ &= \frac{1}{2} \text{tr} \left[M^T \frac{\partial}{\partial b_{ij}} (\Lambda B^T)^{-1} \right] \end{aligned}$$

$$\begin{aligned}
&= -\frac{1}{2} \operatorname{tr}\{M^T(BAB^T)^{-1} \left[\frac{\partial}{\partial b_{ij}} (BAB^T) \right] (BAB^T)^{-1}\} \quad (\text{Lemma 2}) \\
&= -\frac{1}{2} \operatorname{tr}\{M^T(BAB^T)^{-1} \left[\frac{\partial B}{\partial b_{ij}} AB^T + BA \frac{\partial B^T}{\partial b_{ij}} \right] (BAB^T)^{-1}\} \\
&= -\frac{1}{2} \operatorname{tr}\left\{ \frac{\partial B}{\partial b_{ij}} AB^T (BAB^T)^{-1} M^T (BAB^T)^{-1} \right\} \\
&\quad - \frac{1}{2} \operatorname{tr}\left\{ (BAB^T)^{-1} M^T (BAB^T)^{-1} BA \frac{\partial B^T}{\partial b_{ij}} \right\} \\
&= -\operatorname{tr}\left\{ \frac{\partial B}{\partial b_{ij}} AB^T (BAB^T)^{-1} M^T (BAB^T)^{-1} \right\} \\
&= -\gamma_{ji}
\end{aligned}$$

where $(\gamma_{ij}) = AB^T (BAB^T)^{-1} M^T (BAB^T)^{-1}$ so that the Lemma follows since

$$\left(\frac{\partial \Phi_2}{\partial B} \right)^T = \left(\frac{\partial \Phi_2}{\partial b_{ij}} \right)^T = -(\gamma_{ji})^T = -(\gamma_{ij}) = -AB^T (BAB^T)^{-1} M^T (BAB^T)^{-1}$$

Now define the scalar

$$\Phi_3 = \operatorname{tr}[M^T(BDB^T)^{-1}]$$

and we use the notation $\frac{\partial \Phi_3}{\partial D}$ to denote the matrix of partial derivatives

$$\left(\frac{\partial \Phi_3}{\partial d_{ij}} \right) \quad \text{where } D = (d_{ij})$$

Lemma 4 - If $\Phi_3 = \operatorname{tr}[M^T(BDB^T)^{-1}]$, then

$$\frac{\partial \Phi_3}{\partial D} = -B^T (BDB^T)^{-1} M^T (BDB^T)^{-1} B \quad \text{so that whenever}$$

$$BB^T = I_k, \quad \phi_3 = -\text{tr}[BD \frac{\partial \phi_3}{\partial D} B^T]$$

$$\begin{aligned} \text{Proof: } \frac{\partial \phi_3}{\partial d_{ij}} &= \text{tr}[M^T \frac{\partial}{\partial d_{ij}} (BDB^T)^{-1}] \\ &= -\text{tr}\{M^T (BDB^T)^{-1} [\frac{\partial}{\partial d_{ij}} (BDB^T)] (BDB^T)^{-1}\} \\ &= -\text{tr}\{M^T (BDB^T)^{-1} (B \frac{\partial D}{\partial d_{ij}} B^T) (BDB^T)^{-1}\} \end{aligned}$$

But for any two matrices A_1, A_2 ,

$$\text{tr}(A_1 A_2) = \text{tr}(A_2 A_1) \quad \text{whenever both matrix products are defined;}$$

thus letting

$$A_1 = M^T (BDB^T)^{-1} B \quad \text{and} \quad A_2 = \frac{\partial D}{\partial d_{ij}} B^T (BDB^T)^{-1},$$

it follows

$$\frac{\partial \phi_3}{\partial d_{ij}} = -\text{tr}\left\{ \frac{\partial D}{\partial d_{ij}} B^T (BDB^T)^{-1} M^T (BDB^T)^{-1} B \right\}$$

and as in Lemmas 1 and 3 it follows

$$\frac{\partial \phi_3}{\partial D} = \left(\frac{\partial \phi_3}{\partial D} \right)^T = -B^T (BDB^T)^{-1} M^T (BDB^T)^{-1} B$$

Lemma 5 - If $\phi_4 = \ln|BAB^T|$ corresponds to the natural logarithm of the determinant of BAB^T , then

$$\left(\frac{\partial \phi_4}{\partial B} \right)^T = AB^T (BAB^T)^{-1}$$

and thus $B \left(\frac{\partial \Phi_4}{\partial B} \right)^T = I_k$

Proof: Let $\lambda_1, \dots, \lambda_k$ be the strictly positive eigenvalues of BAB^T , so that

$$\Phi_4 = \frac{1}{2} \ln |BAB^T| = \frac{1}{2} \ln(\lambda_1, \dots, \lambda_k)$$

and thus

$$\begin{aligned} \frac{\partial \Phi_4}{\partial b_{ij}} &= \frac{1}{2} \frac{\frac{\partial \lambda_1}{\partial b_{ij}} \lambda_2 \dots \lambda_k}{\lambda_1 \dots \lambda_k} + \dots + \frac{\lambda_1 \dots \lambda_{k-1} \frac{\partial \lambda_k}{\partial b_{ij}}}{\lambda_1 \dots \lambda_k} \\ &= \frac{1}{2} \frac{\frac{\partial \lambda_1}{\partial b_{ij}}}{\lambda_1} + \frac{\frac{\partial \lambda_2}{\partial b_{ij}}}{\lambda_2} + \dots + \frac{\frac{\partial \lambda_k}{\partial b_{ij}}}{\lambda_k} \\ &= \frac{1}{2} \operatorname{tr} \left\{ W^{-1} \frac{\partial W}{\partial b_{ij}} \right\} \quad \text{where} \end{aligned}$$

$$W = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_k \end{pmatrix} \quad \text{is a diagonal matrix}$$

of eigenvalues of BAB^T

But since (BAB^T) is a real symmetric matrix, there exists an orthogonal matrix U satisfying

$$U(BAB^T)U^T = W \quad \text{and} \quad UU^T = I_k$$

(Note $(BAB^T)^{-1} = U^T W^{-1} U$). Thus

$$\begin{aligned} \frac{\partial W}{\partial b_{1j}} &= \frac{\partial U}{\partial b_{1j}} (BAB^T) U^T + U \left[\frac{\partial}{\partial b_{1j}} (BAB^T) \right] U^T \\ &\quad + U (BAB^T) \frac{\partial U^T}{\partial b_{1j}} \end{aligned}$$

and thus

$$\begin{aligned} U^T \frac{\partial W}{\partial b_{1j}} U &= U^T \frac{\partial U}{\partial b_{1j}} (BAB^T) + \frac{\partial}{\partial b_{1j}} (BAB^T) \\ &\quad + (BAB^T) \frac{\partial U^T}{\partial b_{1j}} U \end{aligned}$$

But

$$\begin{aligned} \frac{\partial \Phi_4}{\partial b_{1j}} &= \frac{1}{2} \text{tr} \{ W^{-1} \frac{\partial W}{\partial b_{1j}} \} \\ &= \frac{1}{2} \text{tr} \{ U^T W^{-1} U U^T \frac{\partial W}{\partial b_{1j}} U \} \\ &= \frac{1}{2} \text{tr} \{ (BAB^T)^{-1} [U^T \frac{\partial U}{\partial b_{1j}} (BAB^T) + \frac{\partial}{\partial b_{1j}} (BAB^T) + (BAB^T) \frac{\partial U^T}{\partial b_{1j}} U] \} \\ &= \frac{1}{2} \text{tr} (U^T \frac{\partial U}{\partial b_{1j}} + \frac{\partial U^T}{\partial b_{1j}} U) + \frac{1}{2} \text{tr} [(BAB^T)^{-1} \frac{\partial}{\partial b_{1j}} (BAB^T)] \end{aligned}$$

But since $U^T U = I_k$, it follows

$$U^T \frac{\partial U}{\partial b_{1j}} + \frac{\partial U^T}{\partial b_{1j}} U = 0, \quad \text{so that}$$

$$\begin{aligned}\frac{\partial \phi_4}{\partial b_{ij}} &= \frac{1}{2} \operatorname{tr}[(BAB^T)^{-1} \frac{\partial}{\partial b_{ij}}(BAB^T)] \\ &= \operatorname{tr}\left[\frac{\partial B}{\partial b_{ij}} AB^T (BAB^T)^{-1}\right] \text{ so that}\end{aligned}$$

$$\left(\frac{\partial \phi_4}{\partial B}\right)^T = AB^T (BAB^T)^{-1}, \text{ completing the proof.}$$

Now, recall the definition of the function

$$\phi = \operatorname{tr}(BAB^T) - \operatorname{tr}\{M^T[(BAB^T)^{-1} - (BDB^T)^{-1} - I_k]\} = 2\phi_1 - 2\phi_2 + \phi_3 + \operatorname{tr}\{M^T\}$$

But

$$\left(\frac{\partial \phi_1}{\partial B}\right)^T = AB^T \quad (\text{Lemma 1})$$

$$\left(\frac{\partial \phi_2}{\partial B}\right)^T = -AB^T (BAB^T)^{-1} M^T (BAB^T)^{-1} \quad (\text{Lemma 3})$$

$$\left(\frac{\partial \phi_3}{\partial B}\right)^T = -2DB^T (BDB^T)^{-1} M^T (BDB^T)^{-1} \quad (\text{Lemma 3})$$

$$\frac{\partial \phi_3}{\partial D} = -B^T (BDB^T)^{-1} M^T (BDB^T)^{-1} B \quad (\text{Lemma 4})$$

$$\frac{\partial \phi_1}{\partial D} = \frac{\partial \phi_2}{\partial D} = 0$$

so that

$$\begin{aligned}\left(\frac{\partial \Phi}{\partial B}\right)^T &= 2 \left(\frac{\partial \Phi_1}{\partial B}\right)^T - 2 \left(\frac{\partial \Phi_2}{\partial B}\right)^T + \left(\frac{\partial \Phi_3}{\partial B}\right)^T \\ &= 2\Lambda B^T [I_k + (B B^T)^{-1} M^T (B B^T)^{-1}] \\ &\quad - 2D B^T (B D B^T)^{-1} M^T (B D B^T)^{-1}\end{aligned}$$

and

$$\left(\frac{\partial \Phi}{\partial D}\right)^T = - B^T (B D B^T)^{-1} M^T (B D B^T)^{-1} B$$

where we have assumed $\frac{\partial M^T}{\partial B} = \frac{\partial M^T}{\partial D} = 0$

ADDITIONAL CONSIDERATIONS

Consider the problem of maximizing

$$X = \text{tr}(B\Lambda B^T)$$

subject to the constraint $I_k - B\Lambda B^T$ is positive definite.

Since $I_k - B\Lambda B^T$ is symmetric, there exists an orthogonal matrix Q satisfying

$$Q(I_k - B\Lambda B^T)Q^T = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_k \end{pmatrix} = S$$

and $QQ^T = I_k$, and S is a diagonal matrix of eigenvalues of $I_k - B\Lambda B^T$.

Thus the constraint is equivalent to $\lambda_i > 0$ for all i . Also,

$$\begin{aligned}
X &= \text{tr}(BAB^T) \\
&= \text{tr}(QBAB^TQ^T) \quad (\text{for any orthogonal matrix } Q) \\
&= \text{tr}(\hat{B}\hat{B}^T)
\end{aligned}$$

where $\hat{B} = QB$ is a k by n matrix

It follows \hat{B} satisfies

$$I_k - \hat{B}\hat{B}^T = S$$

so that the row vectors of \hat{B} may always be chosen Λ orthogonal. Alternately, let

$$\hat{B} = \begin{pmatrix} b_1^T \\ \vdots \\ b_k^T \end{pmatrix}$$

and the constraints are equivalent to

$$b_i^T \Lambda b_j = 0 \quad \begin{array}{l} i = 1, \dots, k-1 \\ j = i + 1, \dots, k \end{array}$$

$$1 - b_i^T \Lambda b_i > 0 \quad i = 1, \dots, k$$

Thus the problem is to maximize

$$X = \text{tr}(\hat{B}\hat{B}^T)$$

subject to the above constraints.

Thus it appears the solution to the problem

$$\max X = \text{tr}(BAB^T)$$

subject to the constraint $I_k - BAB^T$ is positive definite is given by any k eigenvectors e_1, e_2, \dots, e_k of Λ , appropriately "scaled" with scalar α so that

$$1 - \alpha^2 e_i^T \Lambda e_i > 0$$

$$\forall_i$$

where we assume $e_i^T \Lambda e_i = 1$

$$\forall_i$$